



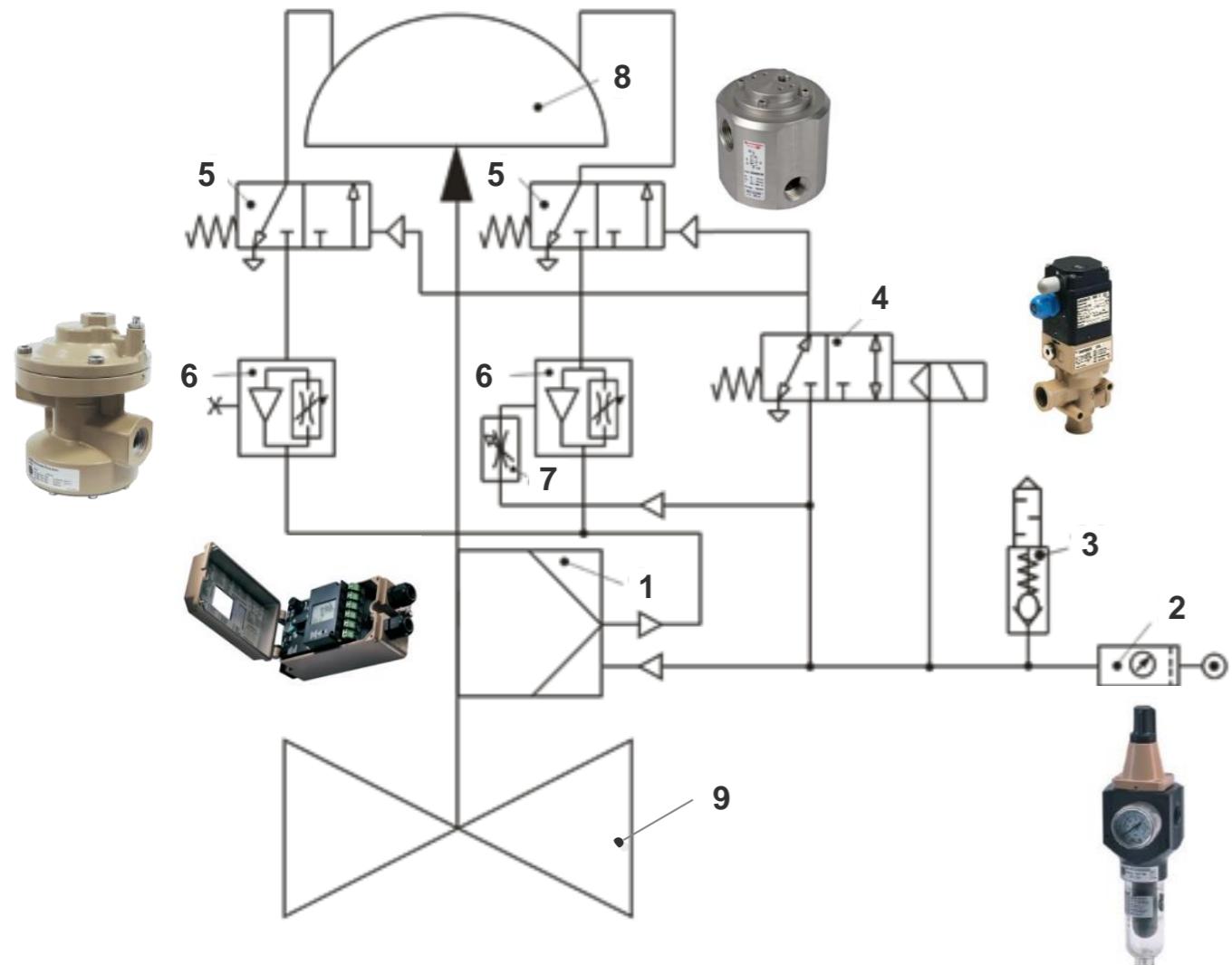
A SUCCESSFUL GROWTH

IVS 2019 - Industrial Valve Summit Conference
Bergamo (Italy) - May 22/23, 2019

Modeling and optimization of a pneumatic control valve assembly

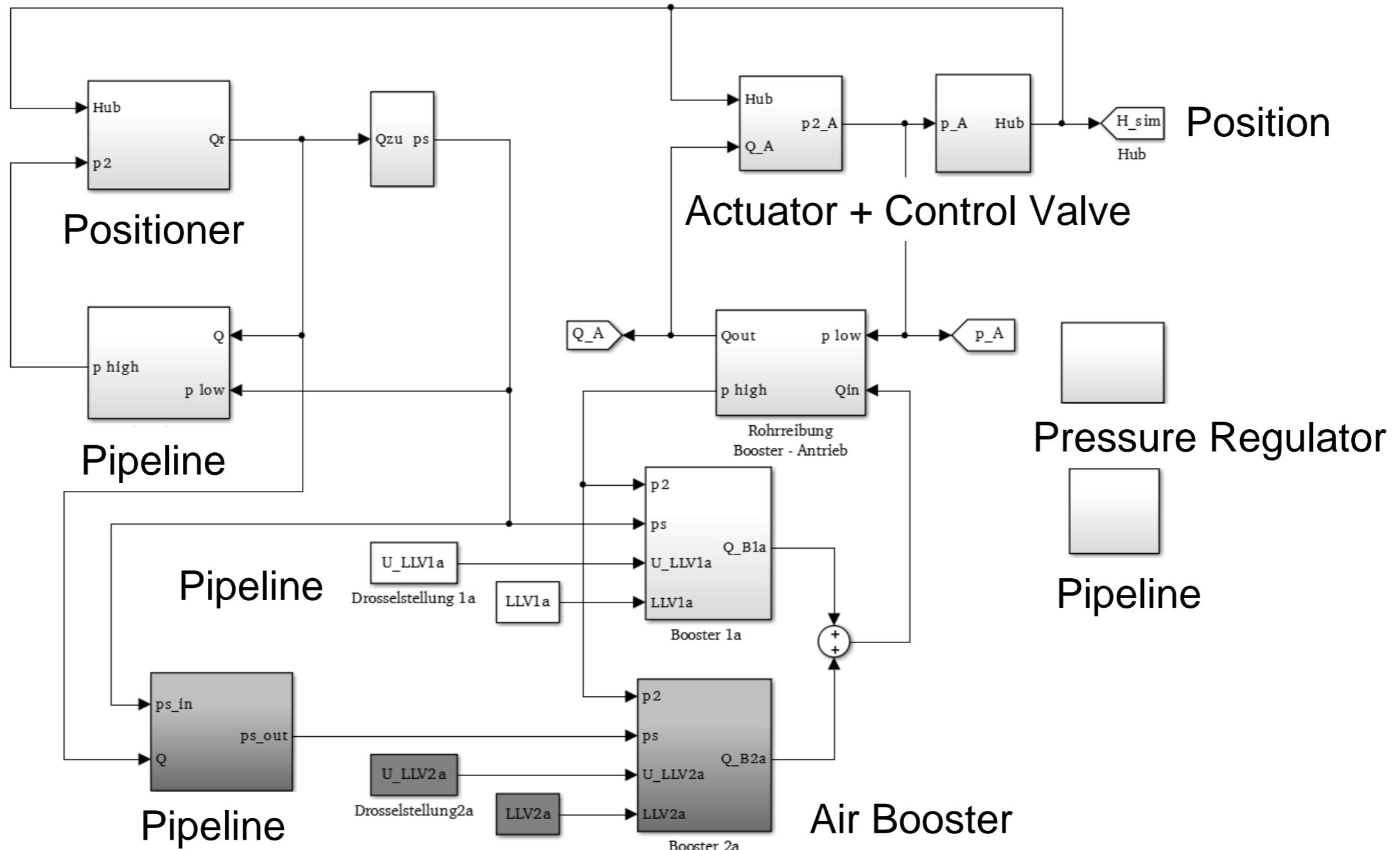
Baihua Sun
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Pneumatic control valve assembly

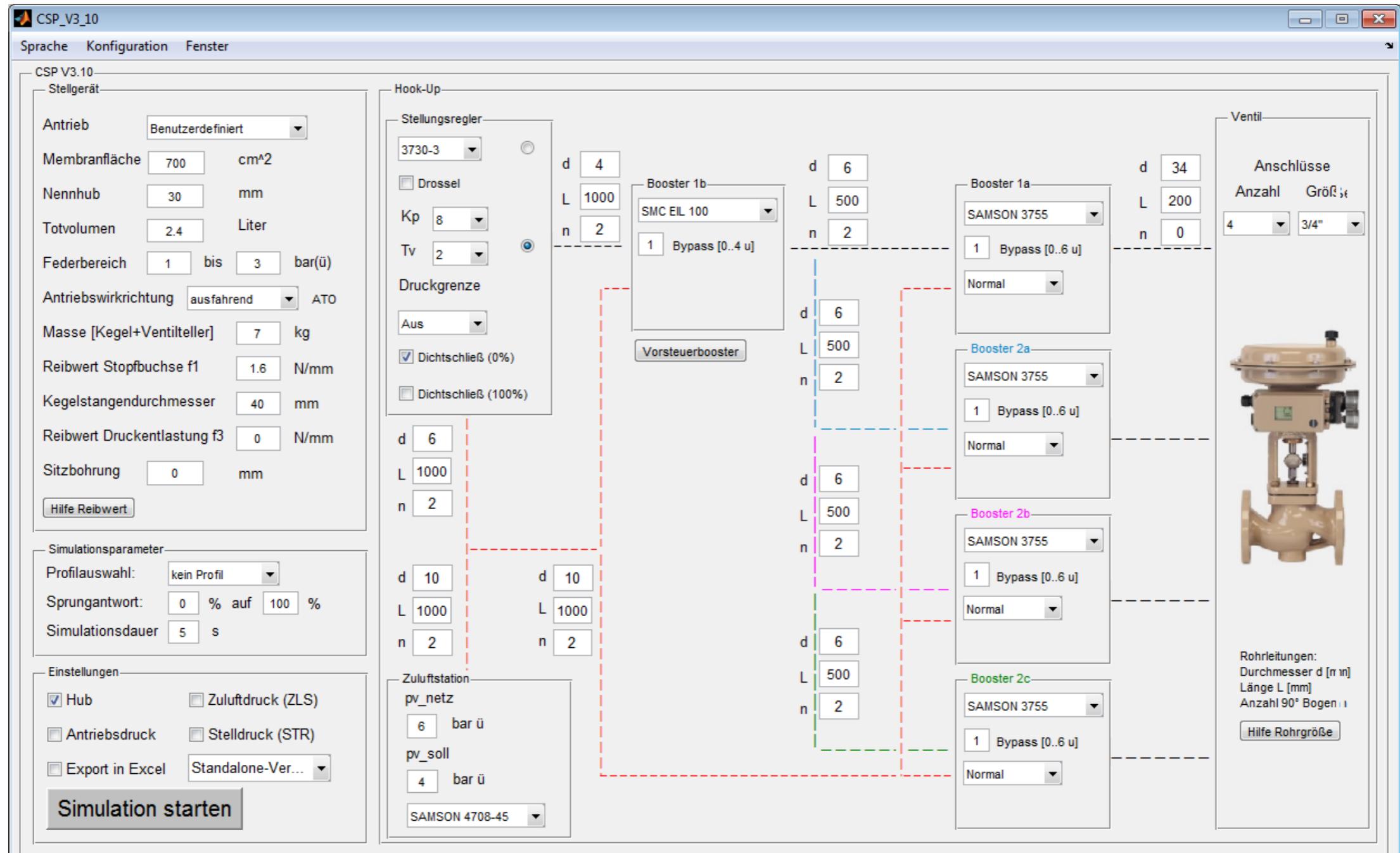


1. Electro-pneumatic positioner
2. Supply pressure regulator
3. Relief valve
4. Solenoid valve
5. Poppet valve
6. Air Booster
7. Throttle valve
8. Pneumatic actuator
9. Control valve

Modeling

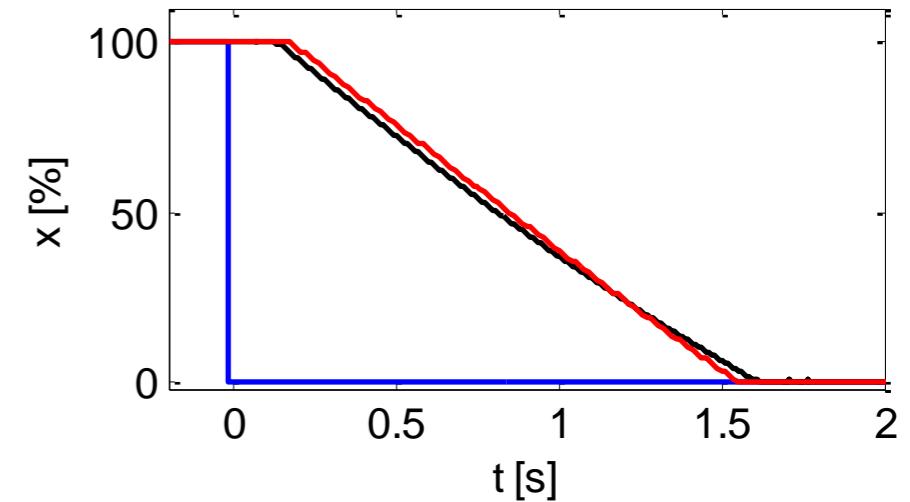
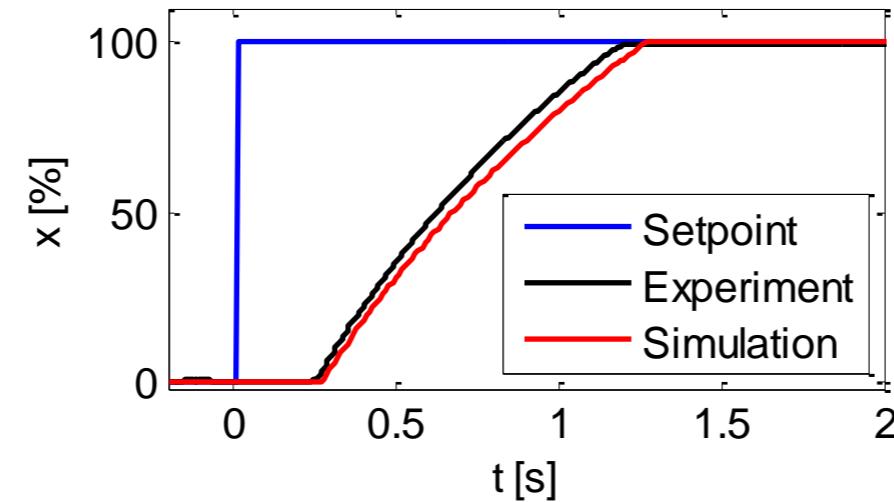
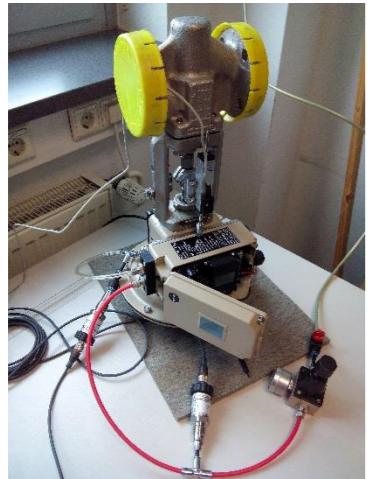


Modeling

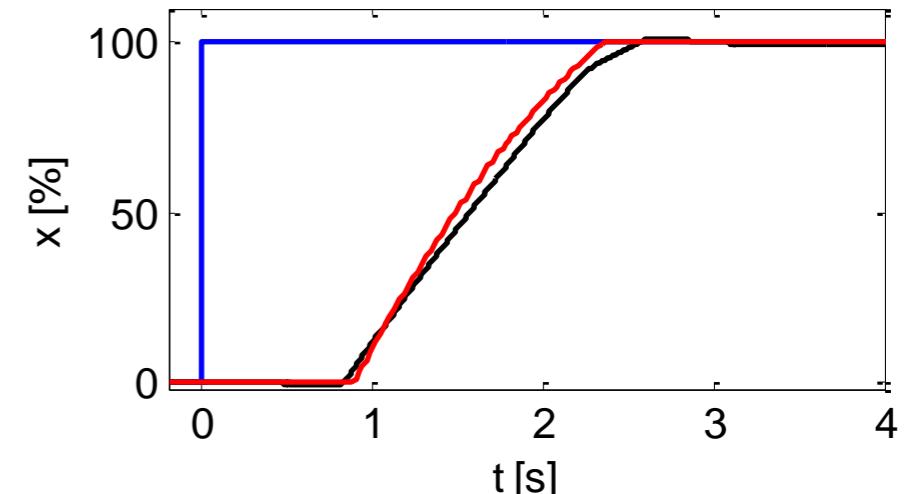
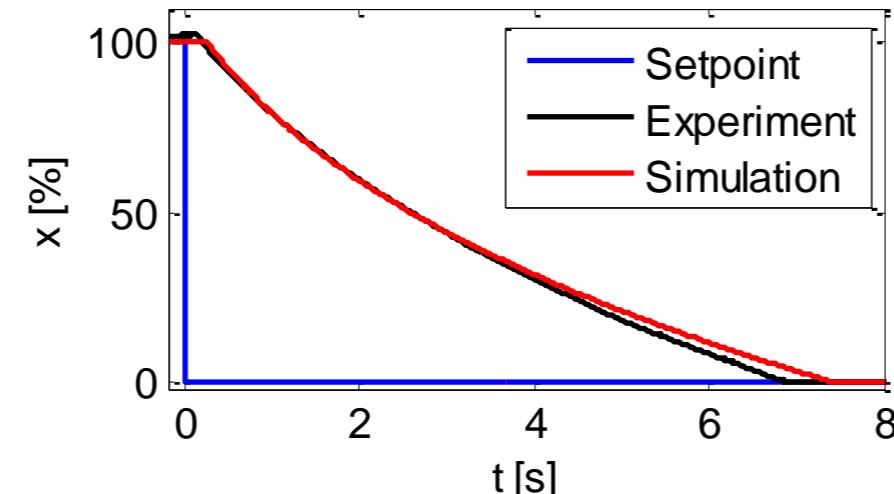


Modeling

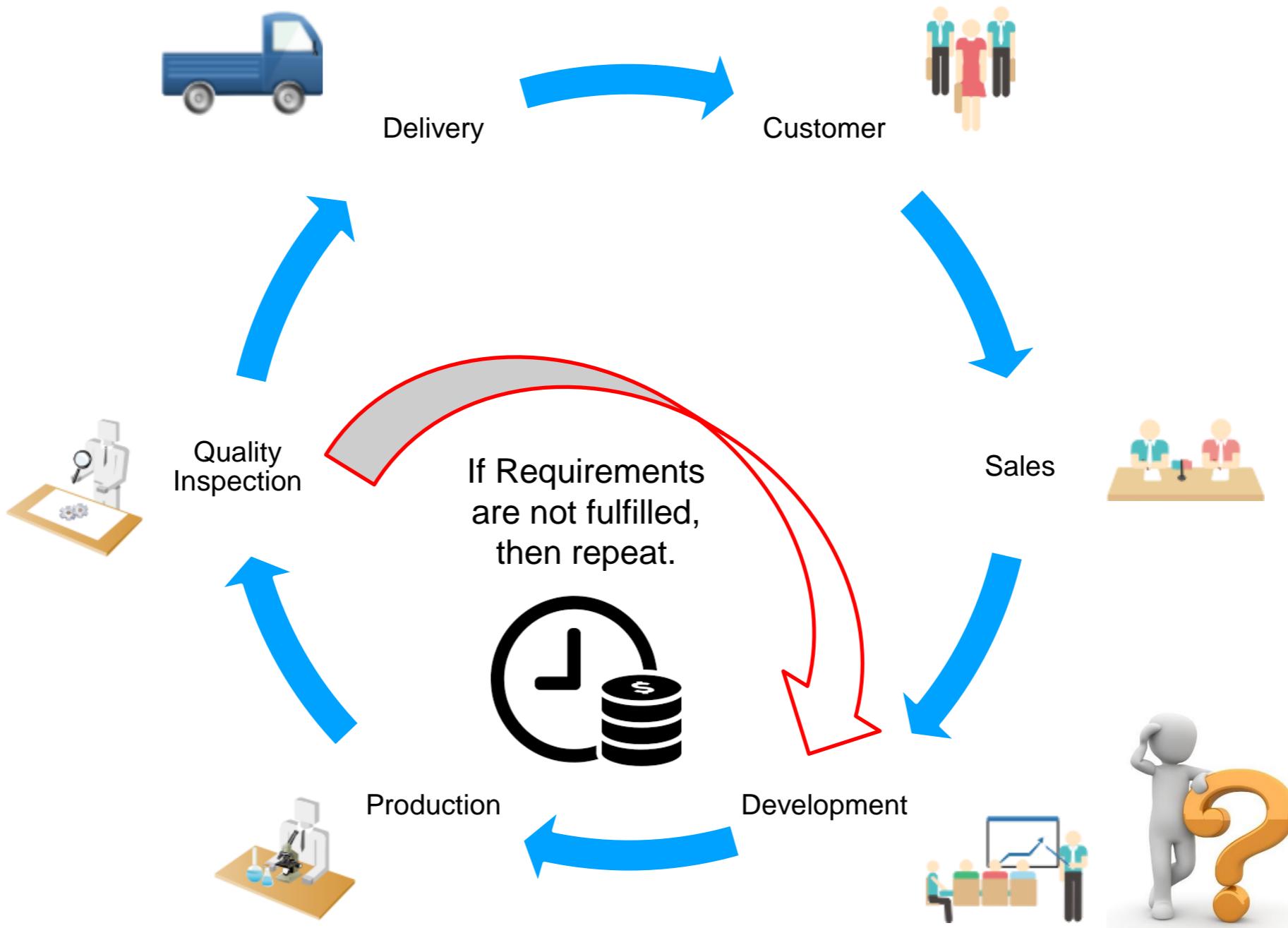
Example 1



Example 2



Optimization



Optimization

Optimization variables

x_1	Amount of booster	$x_1 \in [0, 1, 2, \dots, 8]$	integer
x_2	Bypass	$x_2 \in [0, 6]$	continuous
x_2	Discretized Bypass	$x_2 \in [0, 0.25, 0.5, \dots, 5.75, 6]$	discrete

MINLP-Problem

Boundary conditions

1	y_1	Stroking time_(opening)	$0 \leq y_1 \leq a_1 y_{1max}$
2	y_2	Stroking time_(closing)	$0 \leq y_2 \leq a_2 y_{2max}$
3	y_3	Overshoot	$y_3 \leq a_3 y_{3max}$
4	y_4	Remaining control deviation	$ y_4 \leq a_4 y_{4max}$
5	x_2	Bypass	$x_2 \geq 0.5$

Objective functions

1	$\min J_1^* = (a_1 y_{1max} - y_1)/a_1 y_{1max}$
2	$\min J_2^* = (a_2 y_{2max} - y_2)/a_2 y_{2max}$
3	$\min J_3^* = y_3/a_3 y_{3max}$
4	$\min J_4^* = x_1/8$

scalarization methods with
normalized weighting factors w_i^*

$$\min J(\mathbf{x}) = \sum p_i w_i^* J_i^*(\mathbf{x})$$

Optimization

Heuristic method „Tabu Search“

Step 1: Initialization

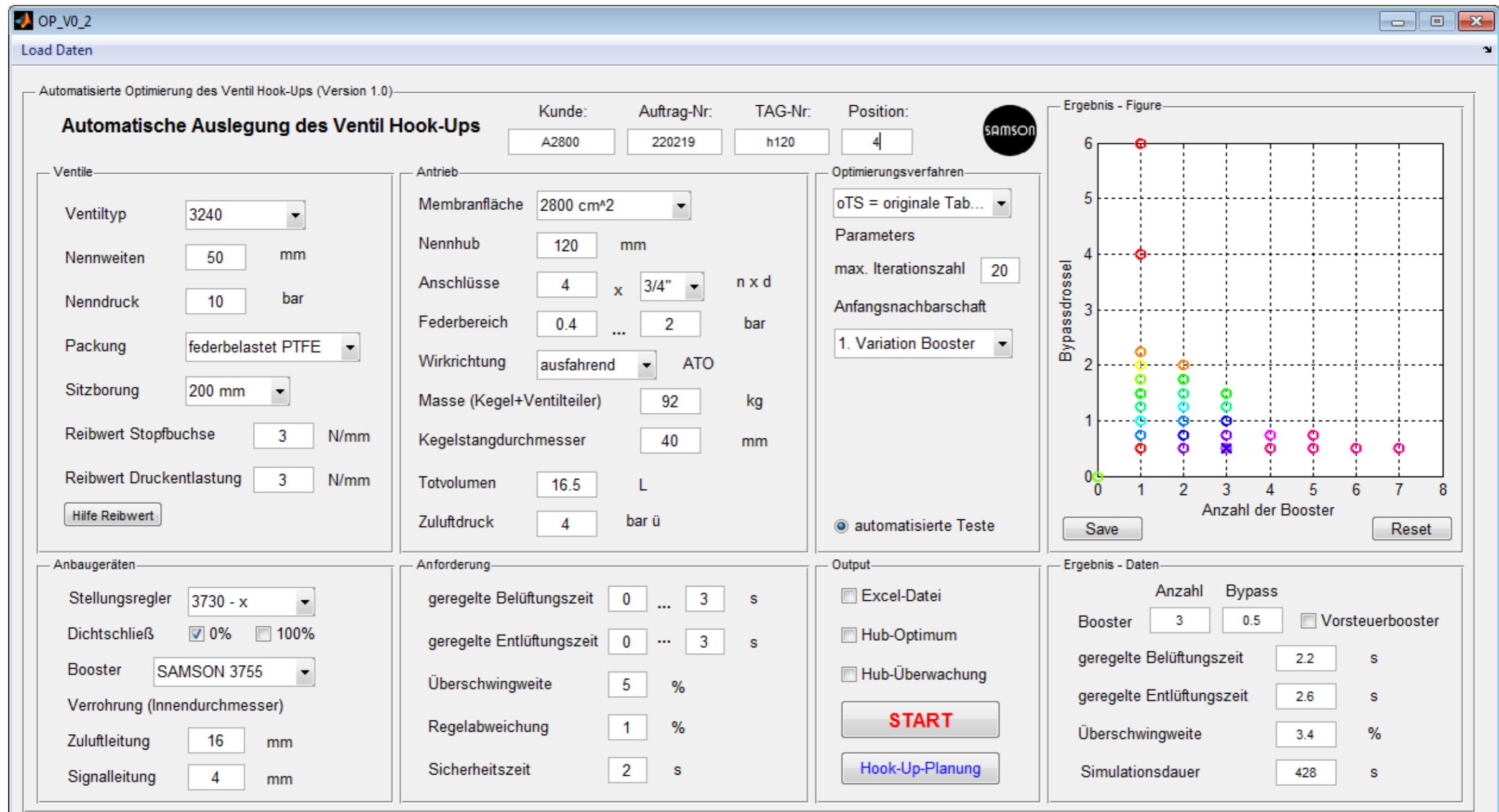
- Define an initial solution (or candidate) x_0
- Set the current solution $x = x_0$
- The best objective function value is stored in the parameter $J_{best} = J(x)$, $x_{best} = x$
- Initial tabu list $TL = \emptyset$

Step 2: Iteration

- Define the neighborhood of the current solution $N(x)$
- Select the best solution $x' = \operatorname{argmin}_{x \in L'}(J(x))$ and $L' = N(x) - TL$
- Update $TL = TL \cup \{x'\}$
- If $J(x') < J_{best}$, then set $J_{best} = J(x')$, $x_{best} = x'$

Until a stopping criterion is met, then return the best value and the best solution as result

Optimization



Thank you!

Do you have questions?

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